```
end 
xr = x1;for i = 1:11 xrold = xr; 
 xr = (x1 + xu)/2;if xr \sim= 0, ea = abs((xr - xrold)/xr) * 100; end
  test = fTa(xl, osf) * fTa(xr, osf);
   if test < 0 
    xu = xr; elseif test > 0 
    x1 = xr; else 
    ea = 0; end 
end 
TC = xr - 273.15;end 
function f = fTa(Ta, osf)f = -139.34411 + 1.575701e5/Ta - 6.642308e7/Ta^2; 
f = f + 1.2438e10/Ta^3 - 8.621949e11/Ta^4;f = f - log(osf);
```
The function can be used to evaluate the test cases:

```
>> TempEval(8) 
ans = 
   26.7798 
>> TempEval(10) 
ans = 
   15.3979 
>> TempEval(14) 
ans = 
     1.5552
```
**5.10 (a)** The function to be evaluated is

$$
f(y) = 1 - \frac{400}{9.81(3y + y^2 / 2)^3} (3 + y)
$$

A graph of the function indicates a positive real root at approximately 1.5.



**(b)** Using bisection, the first iteration is

$$
x_r = \frac{0.5 + 2.5}{2} = 1.5
$$

*f* (0.5) *f* (1.5) = −32.2582(−0.030946) = 0.998263

Therefore, the root is in the second interval and the lower guess is redefined as  $x_l = 1.5$ . The second iteration is

$$
x_r = \frac{1.5 + 2.5}{2} = 2
$$
  

$$
\varepsilon_a = \left| \frac{2 - 1.5}{2} \right| 100\% = 25\%
$$

 $f(1.5) f(2) = -0.030946(0.601809) = -0.018624$ 

Therefore, the root is in the first interval and the upper guess is redefined as  $x_u = 2$ . The remainder of the iterations are displayed in the following table:



After eight iterations, we obtain a root estimate of **1.5078125** with an approximate error of  $0.52%$ .

**(c)** Using false position, the first iteration is

$$
x_r = 2.5 - \frac{0.81303(0.5 - 2.5)}{-32.2582 - 0.81303} = 2.45083
$$

$$
f(0.5) f(2.45083) = -32.25821(0.79987) = -25.80248
$$

Therefore, the root is in the first interval and the upper guess is redefined as  $x_u = 2.45083$ . The second iteration is

$$
x_r = 2.45083 - \frac{0.79987(0.5 - 2.45083)}{-32.25821 - 0.79987} = 2.40363
$$

$$
\varepsilon_a = \left| \frac{2.40363 - 2.45083}{2.40363} \right| 100\% = 1.96\%
$$

*f* (0.5) *f* (2.40363) = −32.2582(0.78612) = −25.35893

The root is in the first interval and the upper guess is redefined as  $x_u = 2.40363$ . The remainder of the iterations are displayed in the following table:



After ten iterations we obtain a root estimate of **2.09077** with an approximate error of 1.59%. Thus, after ten iterations, the false position method is converging at a very slow pace and is still far from the root in the vicinity of 1.5 that we detected graphically.

Discussion: This is a classic example of a case where false position performs poorly and is inferior to bisection. Insight into these results can be gained by examining the plot that was developed in part **(a)**. This function violates the premise upon which false position was based–that is, if  $f(x_u)$  is much closer to zero than  $f(x_l)$ , then the root is closer to  $x_u$  than to  $x_l$ (recall Fig. 5.8). Because of the shape of the present function, the opposite is true.